

Hands-on Running Exercise: Nonlinear simulations of peeling-ballooning modes

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The basic set of equations is found for nonlinear simulations of non-ideal MHD peeling-ballooning modes

$$\frac{\partial \varpi}{\partial t} + v_E \cdot \nabla \varpi = B_0^2 \nabla_{\parallel} \left(\frac{j_{\parallel}}{B_0} \right) + 2b_0 \times \kappa \cdot \nabla P,$$

$$\frac{\partial P}{\partial t} + v_E \cdot \nabla P = 0,$$

$$\frac{\partial A_{\parallel}}{\partial t} = -\nabla_{\parallel} (\phi + \Phi_0) + \frac{\eta}{\mu_0} \nabla_{\perp}^2 A_{\parallel} - \frac{\eta_H}{\mu_0} \nabla_{\perp}^4 A_{\parallel},$$

$$\varpi = \frac{n_0 M_i}{B_0} \left(\nabla_{\perp}^2 \phi + \frac{1}{n_0 Z_i e} \nabla_{\perp}^2 P \right),$$

$$j_{\parallel} = J_{\parallel 0} - \frac{1}{\mu_0} \nabla_{\perp}^2 A_{\parallel}, v_E = \frac{1}{B_0} b_0 \times \nabla (\phi + \Phi_0)$$

Non-ideal physics

✓ Using resistive MHD term, resistivity can renormalized as Lundquist Number

$$S = \mu_0 R v_A / \eta$$

✓ Using hyper-resistivity η_H

$$S_H = \mu_0 R^3 v_A / \eta_H = S / \alpha_H$$

✓ After gyroviscous cancellation, the diamagnetic drift modifies the vorticity and additional nonlinear terms

✓ Using force balance and assuming no net rotation,

$$E_{r0} = (1/N_i Z_i e) \nabla_{\perp} P_{i0}$$

The normalized basic set of equations

Define typical length scale \bar{L} , timescale \bar{T} and magnetic field \bar{B} , $\bar{V}_A = \bar{B}/\sqrt{\mu_0\rho} = \bar{L}/\bar{T}$.

$$\hat{t} = \frac{t}{\bar{T}} \quad \hat{B} = \frac{B}{\bar{B}} \quad \hat{\nabla} = \bar{L}\nabla \quad \hat{\kappa} = \bar{L}\kappa$$

$$\hat{U} = \bar{T}U \quad \hat{\psi} = \frac{\psi}{\bar{L}} \quad \hat{P} = \frac{2\mu_0 P}{\bar{B}^2} \quad \hat{J}_{\parallel} = -\frac{\mu_0 \bar{L}}{B_0} J_{\parallel} \quad \hat{\phi} = \frac{\phi}{V_A \bar{L} B_0}$$

$$\frac{\partial U}{\partial t} + v_E \cdot \nabla U = B_0^2 \nabla_{\parallel} j_{\parallel} + b_0 \times \kappa \cdot \nabla P,$$

$$\frac{\partial P}{\partial t} + v_E \cdot \nabla P = 0,$$

$$\frac{\partial \psi}{\partial t} = -\nabla_{\parallel}(\phi + \Phi_0) + \frac{1}{S} \nabla_{\perp}^2 \psi - \frac{1}{S_H} \nabla_{\perp}^4 \psi,$$

$$U = \left(\nabla_{\perp}^2 \phi + \frac{1}{\omega_{ci} T} \nabla_{\perp}^2 P_i \right), A_{\parallel} = -B_0 \psi$$

$$j_{\parallel} = \nabla_{\perp}^2 \psi, v_E = b_0 \times \nabla(\phi + \Phi_0)$$

Non-ideal physics

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Boundary conditions

On the inner (core) boundary, the conditions applied are

$$\omega = 0 \quad \frac{\partial \phi}{\partial x} = 0, \nabla_{\perp}^2 \phi = 0 \quad j_{\parallel} = 0 \quad \frac{\partial^2 A_{\parallel}}{\partial x^2} = \frac{\partial A_{\parallel}}{\partial x} = 0$$

and outer (vacuum) boundaries are

$$\omega = 0 \quad \frac{\partial \phi}{\partial x} = 0, \nabla_{\perp}^2 \phi = 0 \quad j_{\parallel} = 0 \quad \nabla_{\perp}^2 A_{\parallel} = 0$$

Running a simulation

```
hyperion0:xu(xu)> git clone git://github.com/bendudson/BOUT-1.0.git
```

```
hyperion0:xu(xu)> cd BOUT-1.0
```

```
hyperion0:xu(BOUT-1.0)>source configure.hyperion.tcsh
```

```
hyperion0:xu(BOUT-1.0)>gmake
```

```
hyperion0:xu(BOUT-1.0)> cd examples/elm-pb
```

```
hyperion0:xu(elm-pb)> gmake
```

```
hyperion0:xu(elm-pb)> srun -n16 ./elm_pb
```

Running a simulation

```
hyperion0:xu(elm-pb)>idl
IDL> loadct, 39
IDL> device, decomposed=0
IDL> tek_color
IDL> g=file_import("data/cbm18_dens8.grid_nx68ny64.nc")
IDL>; to plot grid
IDL> plot, g.rxy, g.zxy, /iso, psym=3
IDL> contour2, g.bpxy, g.rxy, g.zxy, nlev=30,/fil,/iso, tit="poloidal B field"

IDL> p = collect(path="data", var="P")
IDL> moment_xyzt, p, rms=rms
IDL> plot, deriv(aalog(rms[40,32,*]))
IDL>
```

- For low resolution mesh $nx=68$, `data/cbm18_dens8.grid_nx68ny64.nc`, the growth rate is $0.275002 * \text{Alfven time}$.
- For high resolution mesh $nx=516$, `data/cbm18_8_y064_x516_090309.nc`, the growth rate is $0.186655 * \text{Alfven time}$.
- The difference is 47%.

Elm-pb running options

✓ To advance the system state in time, BOUT++ uses the CVODE package with the Newton Krylov BDF implicit method

✓ The spatial derivatives are discretized with finite differences. There is a range of finite difference schemes chosen at run time

➤ 4th order central difference

➤ 3rd order WENO.

✓ Automatically handles details of parallel simulation with 2D domain decomposition

☞ NXPE

☞ NYPE

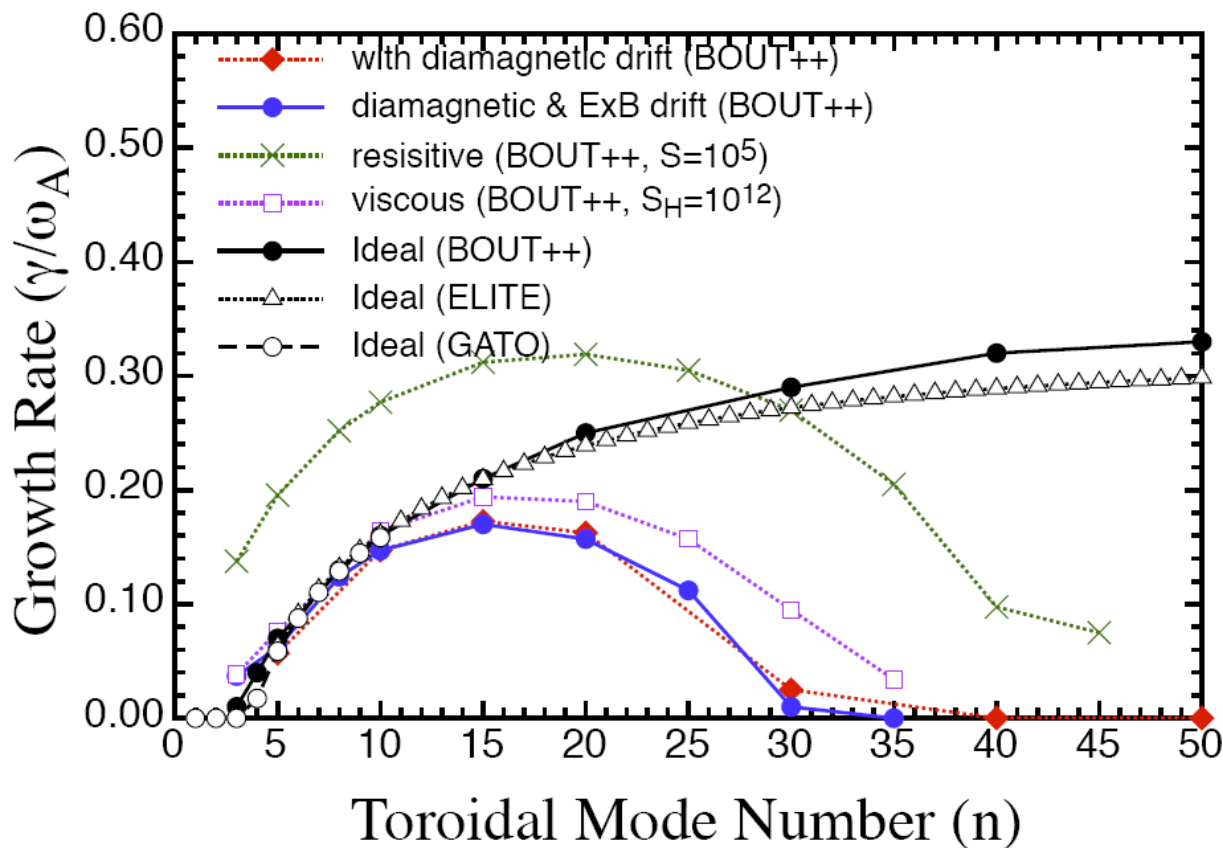
✓ Toroidal segment, zperiod=n, the toroidal mode number

✓ zperiod = 5

✓ Filter option: keep only one mode for linear comparison

✓ Hyper-resistivity for nonlinear ELM simulation

A good agreement for an ideal MHD model is shown between GATO, ELITE, and BOUT++ codes



$$\frac{D}{Dt} = \frac{\partial}{\partial t} + v_E \cdot \nabla,$$

$$v_E = \frac{1}{B_0} b_0 \times \nabla \phi - \frac{E_{r0}}{B_0},$$

$$E_{r0} = (1/N_i Z_i e) \nabla_r P_{i0}$$

$$\frac{\partial A_{||}}{\partial t} = -\nabla_{||} (\phi + \Phi_0)$$

$$+ \frac{\eta}{\mu_0} \nabla_{\perp}^2 A_{||}$$

$$- \frac{\eta_H}{\mu_0} \nabla_{\perp}^4 A_{||}$$

$$\eta_H = \eta \frac{\mu_e}{v_{ei}}$$

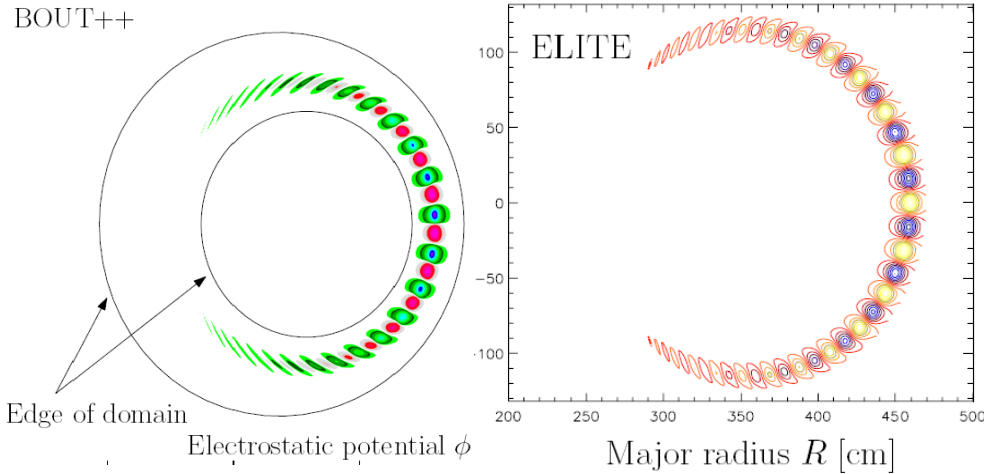
$$S = \mu_0 R v_A / \eta$$

$$S_H = \mu_0 R^3 v_A / \eta_H = S / \alpha_H$$

✓ Resistivity & viscosity destabilizes the ideal modes

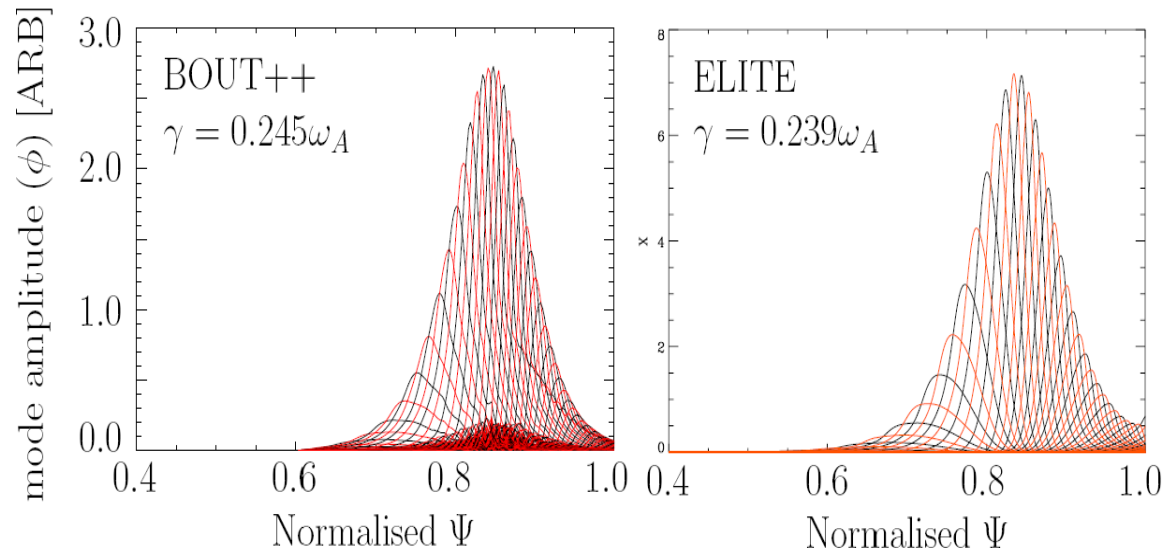
✓ ion diamagnetic drift and ExB drift stabilize the ideal modes

Linear mode structures are similar in BOUT++ and ELITE



BOUT++ and ELITE show the same poloidal wavelength $n=20$

Radial Mode structures are similar in BOUT++ and ELITE



Lundquist number S plays a critical role on nonlinear ideal ballooning mode

Time step collapses at high Lundquist number S w/o η_H

